ASIMOV
STORES

Core Advantages

Ecologically open, seamlessly compatible with all terminals

Full-stack Technology Self-developed

Application System	Inspection System
Digital Middleground	LinkedSight Digital Middleground IoT, Artificial Intelligence, Dynamic Digital Twins
Robot System	RCS system, Map Editing, Task Establishment, Task Planning, Remote Monitoring
Software Algorithm	Mapping, Positioning, Perception, Decision Making, Planning, Control, Recognition Algorithm
Electrical Hardware	Main Controller, Secondary Controller, Domain Controller
Mechanical Structure	Two-wheel Differential Drive Chassis, Four-Wheel Steering and Four-Wheel Drive Chassis
Core Components	Panoramic Camera, Stabilized Gimbal, Servo Motor

Temporal sequence modeling, massive semantic models with human-machine environment interaction

- Fully Automated Modeling: Point Cloud Education Model, Real-time Localization and Mapping, Path modeling based on inspection data
- Intelligent Recognition: Understanding and entering 2 data-object recognitions | Edited annotations | Real-time asset model generation

Dual localization, enhancing robot reliability

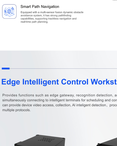
- Image + Point Cloud Fusion "Twin-like" sensors | 3D, super-level positioning health & self-recovery
- Wheel- Speed Motion + IMU + RTK + LiDAR | Multi-sensor fusion positioning | Accurate positioning in road conditions | Large-scale scene support

Dual perception, enabling full-scenario intelligent driving

- 80Y Real-Time Perception: RUN Environmental Perception | Real-time environmental response in motion without line of sight
- Elevation Real-Time Perception: High-precision local terrain modeling

Powerful AI Engine, low-code platform

- Highly intelligent and Self-Learning Capabilities: Data-based algorithms | Online simulations and training | Image, video, and audio



Main Function

Environmental Monitoring
Real-time monitoring of temperature, gas concentrations, sound, and dust levels. Automatic and scheduled inspection tasks.

Image Recognition
Identification of meters, indicator lights, switches, valve positions, cable breakages, water leakage, and other abnormal environments.

Infrared Temperature Measurement
Temperature detection for key components, cables, and equipment. Automatic alarms for overheating and abnormal temperature rises.

Multi Monitoring
Long-distance detection, intrusion detection, safety warning, and linkage with other systems.

Technological Advantage

Powerful Mobility Performance
Equipped with dual-motor drive and 4-point shock-absorbing suspension chassis, it supports stable operation on complex terrains, with a maximum speed of 5 m/s, wide operating temperature, and IP67 protection.

Extreme Environment Adaption
With IP67 protection and a wide operating temperature (-20°F ~120°F), it is resistant to dust/water and can withstand extreme heat, cold, and harsh industrial environments.

AI Recognition
Integrated with multi-modal vision, sound, thermal imaging, and laser recognition sensors, combined with deep learning algorithms, it can accurately identify various abnormal conditions and equipment anomalies.

Superior Imaging Capabilities
Equipped with high-definition visible light and thermal imaging infrared zoom cameras and recognition and measurement algorithms, it can clearly capture and identify small targets and temperature anomalies at long distances.

Smart Path Navigation
Supports multi-point automatic inspection and obstacle avoidance functions. It can also quickly switch to manual remote control mode to meet special inspection requirements.

Technical Parameter

Dimensions (Length×Width×Height)	30.7×24.8×20.5inches	Max Load Capacity	110lbs
Chassis	Four-wheel Four-drive	Max Climbing Slope	45°
Maximum Obstacle Crossing Height	10inches	Turning Radius	0.0ft
Working Mode	APP	Protection Rating	Protection Rating
Positioning Mode	Multi-sensor Fusion	Communication Method	4G/5G/Wi-Fi
Traffic Light Identification System	Colors	Navigation Tools	Positioning Integration, GPS, BDS, GNSS + Visual Navigation + Inertial Navigation
Obstacle Avoidance Type	Ultrasonic	Safety Protection Mode	Light and sound alarm, automatic braking in case of obstacles, remote emergency stop
Environmental Protection Rating	IP67	Operating Temperature	-20°F ~ 120°F
Working Voltage	52.8V	Motor Horsepower	4*5 = 20HP

Edge Intelligent Control Workstation

Provides a complete suite of edge gateways, recognition detection, and device integration, capable of simultaneously connecting to intelligent terminals for scheduling and control. In terms of video processing, it can provide device video access, collection, AI intelligent detection, processing, and distribution functions for multiple protocols.

Workstation Lite

Chassis	Micro Metal Chassis
Dimensions(LxWxH)	12inx7inx8inch
CPU	4Cores
Memory	8G
Hard Drive	64G
GPU	/
Edge Computing Support	No
Cluster Support	No
AI Computing Power	/

Workstation

Chassis	4U Industrial
Dimensions(LxWxH)	48inx20inx17inch
CPU	8Cores
Memory	32G
Hard Drive	512G+SSD
GPU	12GB VRAM
Edge Computing Support	YES
Cluster Support	YES
AI Computing Power	13870 GPS

Outdoor Charging Station

An integrated outdoor charging station for mobile inspection robots, providing safe charging, maintenance, and parking. It incorporates functions such as a micro-weather station, micro-communication station, and security monitoring, featuring the weather monitoring, communication signal relay, fresh networking, and supplementary monitoring coverage.

Dimensions(LxWxH)	20.7inx20.5inx100inch
Weight	661kg
Air Conditioning Mode	Cooling + Heating
Network	Wireless, water immersion, light, environmental sensor
Working Voltage	220V
Positioning Method	Beidou+GPS
Communication Methods	4G/5G/Wi-Fi

Charging Pile

Easy to deploy, it can be put into use by simply fixing it in place and connecting to 220V mains power. With an IP66-rated enclosure, it effectively resists dirt and dust, making it adaptable to various complex environments. Built-in short-circuit and overload detection functions provide comprehensive safety protection.

Dimensions(LxWxH)	40*7.48*48inch
Weight	25kg
Charging Mode	Manual, contact charging
Input Voltage	110Vac/220Vac
Operating Environment	-13°F ~ 122°F

Software Service

| Robot Control System
Inspection handheld terminal, the Robot Control System (RCS), extended RCS modules, unified data management, real-time data collection, flexible expansion and standard data port for upper layer applications.

| LinkedSight Digital Middleground
Key platform integrating IoT, Artificial Intelligence, and Dynamic Digital Twin technologies. Core functionality includes: | Device management | Data visualization | Multi-channel notification | Multi-system integration | Multi-role management

| Inspection System
Core functionality includes: | Inspection task management | Inspection data management | Data analysis | Report generation | Multi-role management

Rapid Development & Integration
With a modular integration method, it enables rapid, standardized technical support. It enables seamless integration of various types of inspection robots, sensors, and third-party systems, and supports rapid customization and secondary development of inspection and inspection applications.

Intelligent O&M Management
Data is securely collected through terminal access devices, together with a powerful AI algorithm library (including 1000+ industrial models), enabling intelligent analysis and early warning of equipment status. Combined with digital twin technology, it enables visualized, remote, and predictive operation and maintenance management, significantly improving operation and maintenance efficiency and reducing labor costs. It is suitable for a wide range of industrial inspection scenarios.

Cost-Effective Decision Making
Combined IoT + digital twin data based on digital twin technology, it builds a virtual mapping model of the physical world, enabling real-time monitoring, simulation, prediction, and optimization of equipment, personnel, and environment status. It can be widely used in industrial parks, smart buildings, urban public safety, and other intelligent scenarios.

Flexible Deployment & Scaling
The terminal control system encapsulates a unified interface for upper-level applications, supporting flexible deployment and rapid integration. It can be quickly adapted to various inspection robots and sensors, and supports secondary development and customization of upper-level applications, enabling rapid iteration and scaling of the application system by the system integrator.

Granular Access Control
Through the unified user authentication (UA) permission mechanism, it enables fine-grained control of data access and operation permissions for different roles, ensuring data security and compliance. It supports flexible configuration of permissions for different roles, meeting the management needs of complex organizational structures.

Software Ecological Architecture

LinkedSight Digital Middleground

The middle platform for robot application technology support and service integrates module functions such as IoT Platform, AI Intelligent computing, Dynamic Digital Twins, and UA Authentication. It serves as the core support for the Security Patrol System and can integrate various types of robots and third-party systems.

Main Function

IoT Platform
The system offers full-lifecycle management for terminals, including device registration, activation, configuration, and decommissioning. It supports multi-protocol access and remote configuration and firmware upgrades, enabling unified device management and real-time status monitoring.

AI Intelligent Computing
The platform is capable of satisfying user requirements and implementing algorithm models and training tasks in research and algorithms in a low-code manner.

Dynamic Digital Twins
Uses an integrated operations suite of scenarios building, data governance, and visualization to build and run twins, enabling efficient programmability. It supports customized digital twin applications for various industries, helping enterprises achieve digital transformation and improve operational efficiency and decision-making. [AI] [Digital Twin]

User Authentication
Provides unified user management and access management (system login, permission control, and operation auditing) for multiple roles, including identity authentication, access control, and intelligent risk identification.

Inspection System

The Inspection System is a management system that empowers business decision-making robots, drones, and various intelligent terminals, applied AI-based analysis to analyze the security status, deliver real-time alerts, and automatically generate inspection reports. It supports multi-terminal access, flexible task scheduling, inspection reports and 3D visualizations. Operators and maintenance personnel can grasp the security status and trends of on-site equipment, facilities, personnel, and environment, which enhances the efficiency of inspection management and reduces labor costs. It is widely used in industrial parks, power grids, transportation, and other industries requiring automated inspections, industrial parks, and power plants.

3+1+1 Intelligent Patrol Mode, Redefine Inspection Work

01 On-Site Modeling
Automatic path planning and task creation, supporting multi-point inspection and scheduled tasks.

02 Mission Orchestration
Flexible task and scene orchestration, supporting multi-point and multi-dimensional inspection.

03 Alert Engine & Linkage
Automatically generates alerts in real time and supports multi-channel notifications.

Robot Inspection Management

Real-time Remote Monitoring

Recorded Data Collection

Data Collection

Value Enhancement

Multi-Channel Notification & Multi-system Integration & Multi-role Management

Problem discovery and notification
Multi-channel alarm notification, supporting SMS, APP, and email.

Centralized & distributed deployment
Flexible deployment options, supporting both centralized and distributed architectures.

Multi-system integration, unified management
Seamlessly connects to third-party systems, enabling unified management.

Main Function

Detection Point Management
Supports the creation, editing, and deletion of inspection points. Basic information, real-time images, historical archives, alarm records, and other information can be viewed for each point. Supports batch import and export of detection points, as well as classification and management by area, equipment, and other dimensions, to facilitate quick retrieval and maintenance.

Anomaly Alarm
Automatically identifies and captures abnormal events (such as trespassing, intrusion, and loitering) during inspections. Alarms are triggered in real time and pushed to the monitoring center. Supports alarm confirmation, processing, and closure, with full traceability. Integrates with third-party systems to enable linkage and rapid response.

Manual Review
The system provides a manual review function to determine the accuracy of alarms and to correct any misidentifications. The assessment of the algorithm's accuracy. Only cases that are confirmed as genuine alarms will be pushed to the user, thereby reducing the interference of false alarms.

Inspection Report
Automatically supports data visualization and inspection results analysis, and generates inspection reports in various formats, including PDF and Excel. Reports can be customized to meet different requirements, and users can customize the report content and time range.

Video Surveillance
It supports multiple split-screen modes and multiple views, enabling simultaneous monitoring of multiple inspection points. Supports PTZ operations. It supports one-click control of the PTZ and automatically returns to the preset position after the operation is completed.

Operation and Maintenance Center
It centrally manages the online status of all devices, including inspection robots and charging stations. It supports remote restart and firmware upgrades, and provides detailed logs. These are overlaid with a map for visual display, enabling rapid fault location and efficient maintenance.

RCS Robot Control System

The RCS is a unified platform-level control and management software integrated within the robot. It enables full-scope control and administration of inspection robots, including reading data from underlying sensors, motor and liquid/gas actuators, robot positioning, navigation and motion control, parameter configuration, hardware self-tests, creating/editing maps, paths and inspection points, formulating inspection tasks, monitoring inspection results, and other critical functions.

LinkedSight Algorithm Library

The library provides over 100 algorithm resources that are ready to use out of the box. These resources will continuously improve as verified data accumulates during operation.

Deployment Method

This system supports both local and public cloud deployments. Based on a high-availability cluster server architecture and a unified resource scheduling and management architecture, it features outstanding disaster - recovery capabilities, reliability, and the ability to scale smoothly. It also enables high-capacity data storage and delivers robust computing power, ensuring seamless support for the Security Patrol System and other application systems.

Local Private Cluster
The Dell System Cloud can be fully deployed locally in the customer's computer room, enabling the construction of a private cloud platform. It supports the deployment of virtual machines and provides elastic and on-demand scaling, enabling complete control over the cloud resources.

Local Dedicated Cluster
A local dedicated server cluster owned by the public cloud by the customer's computer room, integrating the advantages of the two. It supports the deployment of virtual machines, enabling the processing and the operation of business information. Users can flexibly configure and manage cloud resources, enjoying high performance, while benefiting from local security and data sovereignty.

Applications——Energy and Power Industry

Multi-Terminal Robot Patrol Inspection at a Substation in Guangxi

Pain points

- **Inconsistent Coverage:** Various business departments, lacking unity, it's a substation, resulting in difficulties for one device offering a unified inspection standard and coverage.
- **Lack of Collaboration Among Devices:** Inspection robots, drones, and fixed cameras operate independently, making it difficult to achieve data integration and joint scheduling.
- **Poorly-Integrated System:** Data from different devices and communication interfaces, resulting in difficulties in achieving seamless integration and unified management of the system.
- **Insufficient Application and Extension:** Lack of standardized sensors and automated analysis methods, resulting in difficulties in expanding inspection items and improving intelligence.

Deliverables

Developed robot, drone and outdoor situation boards, across LinkedSight Platform, perform system function testing, integration testing, and acceptance testing to ensure the stable operation of the entire system and meet the design requirements.

- Robot Inspection Module: Drone image inspection in the 220kV GIS room and the water pump room, such as reading water data and checking equipment status.
- Drone Equipment Fault Module: Automatic task scheduling, automatic return of the equipment, troubleshoot and other equipment.
- Drone Inspection Module: Automatic task scheduling, automatic return of the equipment, troubleshoot and other equipment.
- Indoor Inspection Module: Computer communication issue and RCSC distribution room of the main control building.

Project value

- Comprehensive and automatic operation and maintenance so that even if the inspection points in the station have a day, reducing the number of manual inspections and labor costs.
- Provides a unified management system based on digital twin, enabling one-screen management for all the devices in the station.
- Integrates intelligent and automatic inspection robots and drones to form a new mode of operation, improving inspection scheduling and emergency response capabilities, and reducing the workload of on-site personnel.
- Provides a unified data connection interface at the system level, enabling standardized access to the third-party management platforms and equipment.
- Integrates a variety of AI recognition algorithms to automatically identify abnormal conditions and equipment anomalies, reducing manual judgment errors.

Applications——Mining Smelting Industry

Robot Automated Inspection Project in a Steel Plant in Guangxi

Pain points

- **Hazardous Working Environment:** Manual inspection is fraught with safety hazards including high temperatures, dust, and toxic gases.
- **Inconsistent Data Coverage:** Data collection is incomplete for traditional approaches. The absence of data such as sound and thermal imaging makes it difficult to identify potential equipment failures.
- **Unstable Performance in Extreme Working Environment:** Conventional robots exhibit poor stability and a high failure rate in environments with high temperatures, dust, and strong electromagnetic fields, leading to frequent operational interruptions and the need for increased manual inspection frequency.

Deliverables

Outdoor situation station, AGS management system, RCS main control system, charging room and its control system, and the corresponding software system.

- Weather station: Temperature detection and wind detection in the fixed furnace and converter areas.

Project value

- The mobile operation ensures autonomously without human intervention, achieving full coverage inspections in any circumstances, and improving inspection efficiency.
- The robots can autonomously return to the charging room for charging, cooling, and dust cleaning, reducing high stability failures and maintenance costs.
- Integrated with the Steel Enterprise Digital Twin platform, it enables real-time viewing of robot operation status, tracking and analysis of inspection reports, and automatic work order generation, forming a closed-loop management system.
- Develops a user-friendly operation and maintenance app, supporting remote control of the robot's operation, viewing and analysis of inspection reports, and receiving alarm notifications, thereby enabling remote management.

Applications——Park Management

Digital Platform Application at a Shanxi Park

Project Background

By integrating the data from various business systems in the park, including production, operation, safety, monitoring, and equipment management, and combining with big data processing technology, a visual digital twin park is created. This enables data-driven management of the park, improving the efficiency of various intelligent applications for smart business.

Key business systems integrated include production management, operation visualization, park environment visualization, equipment management, safety management, video monitoring, intelligent inspection, security management, energy consumption monitoring, equipment maintenance, warehouse management, and logistics management.

Pain Points

- **Poor IoT Sensor construction:** The lack of IoT sensor devices, resulting in difficulties to collect more real-time information about devices and environment.
- **Insufficient Business Integration:** Data is scattered across various systems, making it difficult for managers to obtain a comprehensive view of park operations.
- **Weak Park Inspection and Maintenance Capabilities:** Traditional park management relies on human resources, leading to low overall management efficiency.
- **Lack of Far-Sized Image in The Park:** Park construction in the park is independently constructed, resulting in data isolation between each system.

Advantages of the Solution

- Create a "1+N+X" management model to achieve "overall asset operation and maintenance and security assurance".
- Integrate the data from various business systems in the park, including production, operation, safety, monitoring, and equipment, to form a unified data foundation. Create a visual digital twin park model. It enables data-driven management of the park, improving the efficiency of various intelligent applications for smart business.
- Manage the robot models in terminal management, including the Robot Dog and Quadruped Robot, and the Robot Dog and Quadruped Robot can be remotely controlled and inspected. Integrate the robot's video stream and inspection data into the platform for unified management and display. Use wireless networking and communication technology to achieve real-time data transmission and remote control.
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Applications——Hazardous Chemical Industry

Visualized Digital Management Application in a Smelting Plant in Xinjiang

Project Background

The project provides a solution for a unified digital management system for a smelting park. The management system integrated personnel management, environmental monitoring, and equipment management. It also integrated a comprehensive set of applications, including area-based management, digital twins for high-concentration and high-pressure areas such as gasoline and coke oven gas pressurization stations. The robot is capable of autonomous inspection and data collection, enabling real-time monitoring of the park's operational status. This system helps improve management efficiency, ensure production safety, and provide a scientific basis for personnel management, equipment management, and decision-making.

Pain Points

- **Lack of Visualization:** Visual visualization such as existing process, equipment operation, and machine interaction are missing, resulting in difficulties in monitoring the park's status.
- **Poor Inspection Effect:** In traditional inspection methods, situations such as abnormal operations of key and missed equipment inspections occur frequently.
- **Difficulty in Data Analysis:** Difficult to analyze the data of personnel, equipment, and the production process. There is no scientific basis for management decisions.
- **Poor Emergency Response Ability:** There are significant safety hazards in the high-temperature and hazardous areas, and there is an urgent need for remote robot inspection.

Advantages of the Solution

- Full Lifecycle Equipment Management: An accurate and efficient inspection and operation and maintenance system is established for the entire lifecycle of equipment, from procurement and entry to maintenance and scrapping. This system helps enterprises reduce equipment failure rates, extend equipment service life, and improve overall operational efficiency.
- Precise Personnel Positioning: Using technologies such as UWB high-precision positioning, the system can monitor the location of personnel in real time, which is convenient for the management of personnel positions, inspection paths, and emergency rescue. It can also quickly locate personnel in the event of an accident, improving rescue efficiency.
- Hazardous Warning: Through the analysis of hazardous data, the system issues hazard warnings in advance, improving the prevention of equipment failures, promptly identifying potential equipment hazards, and realizing early detection, early prevention, and early elimination.
- Intelligent Inspection: Intelligent inspection robots can perform autonomous inspection tasks, reducing the work intensity of manual inspections and improving the accuracy and efficiency of inspections.